

Dynamically Scheduling and Maintaining a Flexible Server

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Scheduling and Maintenance

A **flexible** server/machine can handle different types of **jobs**.

- ▶ e.g., different kinds of customers, different products

The service capacity/rate of the server can **deteriorate** over time.

- ▶ e.g., fatigue, wear & tear, needs cleaning

Questions:

1. How should the server's effort be allocated (i.e., **scheduled**)?
2. When should the server be **maintained**?

We consider these questions in the context of a **queueing** system.

Queue with State-Dependent Service Rates

Consider an **M/M/1** queueing system with **two arrival classes**.

For class $i = 1, 2$,

- ▶ arrival rate is λ_i
- ▶ holding cost rate is c_i

The service rates depend on the **server state** $s \in \{1, \dots, S\}$.

- ▶ μ_i^s = class i service rate when server state is s

The **server state evolves** according to a continuous-time Markov chain.

- ▶ jump probabilities $J_{s,t}$, $s, t \in \{1, \dots, S\}$
- ▶ holding time rates α_s , $s \in \{1, \dots, S\}$

Related Work

- ▶ Cai, Hasenbein, Kutanoglu & Liao (2013) consider a closely related 2-class model, with a different cost, service, and degradation structure.

- ▶ Other work in [joint service/production and maintenance](#):
 - ▶ **Single Job Class:** Kaufman & Lewis (2007), Yao (2003), Koyanagi & Kawai (1995)
 - ▶ **Non-Queueing:** Yao, Xie, Fu & Marcus (2005), Iravani & Duenyas (2002), Sloan & Shanthikumar (2000)

Scheduling

For now, assume we only need to decide **how to allocate the server**.

- ▶ At each **decision epoch** (arrival, service completion, server state change), decide which class to serve.

A **policy** for doing this can depend on the current queue lengths and server state, as well as the **history** (past queue lengths, server states, and decisions).

- ▶ $Q_i^\pi(t)$ = number of class i jobs at time t , under policy π

Objective: Find a policy π minimizing the long-run expected average cost

$$\limsup_{T \rightarrow \infty} \frac{1}{T} \mathbb{E} \int_0^T [c_1 Q_1^\pi(t) + c_2 Q_2^\pi(t)] dt$$

Scheduling

Definition

The **$c\mu$ -Rule** is the scheduling policy where

server state is $s \implies$ prioritize class $i^* \in \arg \max_{i=1,2} c_i \mu_i^s$

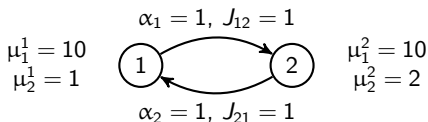
Well-Known: If the server state does not change, then the $c\mu$ -Rule is optimal. (Buyukkoc, Varaiya & Walrand 1985)

Question: Is the $c\mu$ -Rule optimal when the server state changes?

Suboptimality of the $c\mu$ -Rule

Example:

- ▶ arrival rates $\lambda_1 = 5$,
 $\lambda_2 = 0.8$
- ▶ cost rates $c_1 = c_2 = 1$
- ▶ $S = 2$ server states



$$c_1 \mu_1^1 = 10 > 1 = c_2 \mu_2^1$$

$$c_1 \mu_1^2 = 10 > 2 = c_2 \mu_2^2$$

The $c\mu$ -Rule (always prioritize class 1) leads to an **infinite average cost!**

- ▶ (long-run fraction of time busy with class 1) = $\frac{\lambda_1}{10} = \frac{1}{2}$
- ▶ (average class 2 service rate) = $\frac{1}{2} \left(\frac{1}{2} \cdot 1 + \frac{1}{2} \cdot 2 \right) = 0.75 < 0.8 = \lambda_2$

The $c\mu$ -rule is **not optimal**, because the following policy leads to a **finite average cost**:

- ▶ If the server state is s , prioritize class s .

When is the $c\mu$ -Rule optimal?

Theorem

Suppose

$$\mu_1^{s-1} \mu_2^s = \mu_1^s \mu_2^{s-1} \quad \forall s > 1. \quad (1)$$

Then the $c\mu$ -Rule is optimal.

- ▶ (1) means that the ratio between the service rates is constant in s :

$$\mu_1^{s-1}, \mu_2^s > 0 \implies \frac{\mu_1^{s-1}}{\mu_2^{s-1}} = \frac{\mu_1^s}{\mu_2^s}$$

- ▶ Under (1), a variant of the interchange argument in (Nain 1989) can be used to prove the Theorem.

Scheduling and Maintenance

Same **M/M/1** model as before, with the following **modifications**:

- ▶ Additional server state 0 (server is **down for maintenance**)
- ▶ $0 = \mu_i^0 < \mu_i^1 \leq \dots \leq \mu_i^S$ for $i = 1, 2$
 - ▶ $s =$ **condition** of the server
- ▶ **Preventive Maintenance (PM)** when $s > 0$
 - ▶ Send the server to state 0
 - ▶ Incur cost K_{PM}
 - ▶ Maintenance time has general distribution G
- ▶ **Deterioration** when $s > 0$
 - ▶ Server transitions from state s to $s - 1$ at rate α_s
 - ▶ If an uncontrolled transition to server state 0 occurs, the **Corrective Maintenance (CM)** cost K_{CM} is incurred.

Scheduling and Maintenance

A **policy** stipulates, given the current queue lengths, server state, and history of the process, whether to

- ▶ initiate preventive maintenance, or
- ▶ serve one of the classes.

For a policy π ,

- ▶ $Q_i^\pi(t)$ = number of class i jobs at time t , under π
- ▶ $M_{\text{PM}}^\pi(t) = \begin{cases} 1 & \text{if PM is initiated at time } t \text{ under } \pi \\ 0 & \text{otherwise} \end{cases}$
- ▶ $M_{\text{CM}}^\pi(t) = \begin{cases} 1 & \text{if CM is initiated at time } t \text{ under } \pi \\ 0 & \text{otherwise} \end{cases}$
- ▶ t_n^π = time of the n^{th} maintenance initiation, under π

Objective: Find a policy π minimizing the long-run expected average cost

$$\limsup_{T \rightarrow \infty} \frac{1}{T} \mathbb{E} \left[\sum_{n: t_n^\pi \leq T} [K_{\text{PM}} M_{\text{PM}}^\pi(t_n^\pi) + K_{\text{CM}} M_{\text{CM}}^\pi(t_n^\pi)] + \int_0^T \sum_{i=1}^2 c_i Q_i^\pi(t) dt \right]$$

Structure of Optimal Policies

Theorem

Suppose

$$\mu_1^{s-1} \mu_2^s = \mu_1^s \mu_2^{s-1} \quad \forall s > 1,$$

and that there exists a server state s^* such that

$$\frac{\lambda_1}{\sum_{s=s^*}^S (\mu_1^s / \alpha_s)} + \frac{\lambda_2}{\sum_{s=s^*}^S (\mu_2^s / \alpha_s)} < \frac{1}{(1/\alpha_0) + \sum_{s=s^*}^S (1/\alpha_s)}.$$

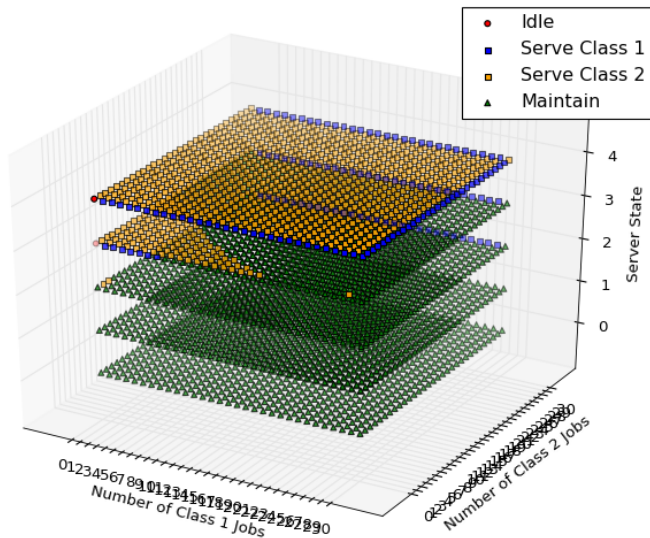
Then there is an optimal policy that

- (i) schedules according to the $c\mu$ -Rule, and
- (ii) makes maintenance decisions monotonically in the server state.

- ▶ “schedules according to the $c\mu$ -Rule” means:
 - ▶ If the policy says to serve a class (rather than do preventive maintenance), use the $c\mu$ -Rule to select which one.
- ▶ “makes maintenance decisions monotonically in the server state” means that for each fixed number of class 1 jobs and number of class 2 jobs in the system,
 - ▶ maintain when server state is $s \implies$ maintain when it is $s - 1$

Structure of Optimal Policies

Example: $c\mu$ -Rule says to prioritize class 2:



Conclusions

We considered a **combined scheduling and maintenance** problem for a queueing system.

Key Takeaways:

- ▶ The **$c\mu$ -Rule** can be very bad.
- ▶ If degradation reduces the service rates by the same percentage, then **attention can be restricted** to policies that
 - ▶ schedule according to the $c\mu$ -Rule, and
 - ▶ call for maintenance monotonically in the server state.

Regarding the structure of optimal or near-optimal policies, **the picture is still very incomplete**.

- ▶ Heavy-traffic approximations?
- ▶ One-step policy improvement?