

EC4480: Image Processing and Recognition

By

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EC4480. Week1: *Color Representation*

Description.

Humans perceive light and colors through two classes of sensors on the retina: "rods", to perceive intensity only, and three classes of "cones" (Red, Green and Blue), to perceive colors. R,G,B are also the basis of video displays and by their combinations all perceivable colors can be displayed. Red, Green and Blue are called the "Primary Colors".

Another set of colors, called "Secondary Colors" are Yellow, Magenta and Cyan. These form the basis of displays based on absorption, such as ink on paper. These are also the ink cartridges you buy for your color printer.

Due to a number of reasons, including the need to be compatible with Black and White displays, rather than using R,G,B components for colors it is better to use Intensity (or Luminance) and then two parameters to describe the color information. This two dimensional color description leads to standard "Chromaticity Diagrams" where all the colors are displayed in a plane, which also shows the result of mixing different colors, as you might have seen when you buy paint in the hardware store.

This representation leads to a number of standards such YUV (used in JPEG), YIQ (used in the NTSC TV standard) and YCbCr. In all these standards the "Y" stands for Intensity (or Luminance) and the other two components describe the color. Different standards vary according to which company developed it.

Course Material:

- PPT Slides:
 - [Color Representation](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/1-Color-Representation.ppt>

- Videos:
 - [Human Color Perception](#) 25.28min
<http://faculty.nps.edu/rcristi/EC4480/videos/1-Color-Representation-Seg1.mp4>

 - [Chromaticity Diagrams](#) 28.31min
<http://faculty.nps.edu/rcristi/EC4480/videos/1-Color-Representation-Seg2.mp4>

 - [Color Coding](#) 20.19min
<http://faculty.nps.edu/rcristi/EC4480/videos/1-Color-Representation-Seg3.mp4>

- Assignment:

- Project 1 in Sakai ([*description*](#))

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment1/EC4480-Assignment-1.docx>

- [Project1 video](#)

25.35min

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment1/Project1.mp4>

EC4480. Weeks2-3: 2D Signals and Systems

Description.

Signals and Basic Processing. A digital image is a matrix of pixels. In particular a color image is a matrix with three dimensions: $N_r \times N_c \times 3$, with N_r , N_c numbers of rows and columns and 3 the color dimension (say R,G,B or any other standard).

It is customary to separate Intensity from Color, so the intensity image (gray scale) is just a regular $N_r \times N_c$ matrix, with two indices. This defines a 2D (for "Two Dimensional") signal as a function of two independent variables, as opposed to a 1D signal, function of one independent variable, such as time.

Basic image processing algorithms are also introduced to detect local features, such as edges which, in turn, are used to identify geometric features such as lines.

Fourier Analysis of 2D Signals and Systems. The concept developed for 1D signals and systems (usually function of time) in previous courses, are extended to 2D signals and systems, where the independent variables are now vertical and horizontal spatial coordinates. In particular concepts like the Fourier Transform, Linear Shift Invariant filtering and Convolution are extended to the 2D domain.

Along similar lines as for 1D time signals, the Fourier Transform is used to identify features of the images with the purpose of classification and/or identification of disturbances. In addition, standard 1D techniques to design filters can be extended easily to the design of 2D filters by a number of 1D to 2D transformations, such as the McClellan Transformation.

Course Material:

- PPT Slides:
 - [2D Signals and Systems](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/2a-2D-Signals-and-Systems.ppt>
 - [2D Fourier Analysis](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/2b-Fourier-Analysis-in-2D.ppt>
- Videos:
 - [Images as 2D Signals](#) 33.44min
<http://faculty.nps.edu/rcristi/EC4480/videos/2a-2D-Signals-Systems-Seg1.mp4>
 - [Simple 2D Filters](#) 30.20min
<http://faculty.nps.edu/rcristi/EC4480/videos/2a-2D-Signals-Systems-Seg2.mp4>
 - [2D Fourier Transform](#) 46.31min
<http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg1.mp4>
 - [2D Sampling Theorem](#) 16.27min
<http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg2.mp4>

- [2D Frequency Response](http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg3.mp4) 20.56min
<http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg3.mp4>
- [2D Discrete Fourier Transform \(DFT\)](http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg4.mp4) 24.28min
<http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg4.mp4>
- [2D Filters](http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg5.mp4) 21.27min
<http://faculty.nps.edu/rcristi/EC4480/videos/2b-Fourier-Analysis-2D-seg5.mp4>
- Assignment:
 - Project 2 in Sakai ([description](#))
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment2/Project2.docx>
 - [Project 2 Video](http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment2/Project2.mp4) 44.22min
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment2/Project2.mp4>
 - Project 2 Video 2
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment2/Project2-Filter.mp4>

EC4480. Weeks4-5: Image Compression by the Discrete Cosine Transform (DCT)

Efficient Signal and Image Representation.. We see image (and also video) compression every day. Whenever we download an image from our digital camera or from the internet and we see it on our screen, we are still amazed at the excellent quality of the result. But if we look even further on the size of the file and we do simple back-of-the-envelope computations, we see that the size of the file is order of magnitudes smaller than what we expect by the 3 bytes per pixel needed to encode luminance and color. This efficiency is due to the application of basic signal representation techniques such as the Discrete Karhunen Loeve Transform (DKLT), and the Discrete Cosine Transform (the DCT, a “cousin” of the FFT).

Entropy as a Measure of Signal Information. The general problem of quantifying how much “information” is in a signal (whether it is a communication signal, or audio or an image) is addressed by using the concept of “entropy”. This concept is introduced from basic concepts and well known formulas of “combinatorics”. It yields a surprisingly simple expression of the information content of any source, in terms of “average number of bits per symbol”, which can be used to assess how much a signal can be compressed without noticeable losses. A commonly used code (the Huffman code) for efficient representation is introduced.

Course Material:

- PPT Slides:
 - [DKLT and DCT](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/3-DKLT-DCT.ppt>
 - [Entropy](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/4-Entropy.ppt>
- Videos:
 - [Discrete Karhunen-Loeve Transform \(DKLT\)](#) 41.24min
<http://faculty.nps.edu/rcristi/EC4480/videos/3-DKLT-DCT-seg1.mp4>
 - [DKLT for 2D Signals](#) 33.37min
<http://faculty.nps.edu/rcristi/EC4480/videos/3-DKLT-DCT-seg2.mp4>
 - [Discrete Cosine Transform \(DCT\)](#) 17.08min
<http://faculty.nps.edu/rcristi/EC4480/videos/3-DKLT-DCT-seg3.mp4>
 - [Transmission of Information](#) 16.21min
<http://faculty.nps.edu/rcristi/EC4480/videos/4-Entropy-seg1.mp4>
 - [Entropy of a Source of Information](#) 30.32min
<http://faculty.nps.edu/rcristi/EC4480/videos/4-Entropy-seg2.mp4>
 - [Entropy Coding: Huffman Code](#) 40.49min
<http://faculty.nps.edu/rcristi/EC4480/videos/4-Entropy-seg3.mp4>

- Assignment:

- Project 3 in Sakai ([*description*](#))

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment3/Project3.docx>

- [Project 3 Video 1](#)

33.55min

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment3/Project3-seg1.mp4>

- [Project 3 Video 2](#)

41.58min

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment3/Project3-seg2.mp4>

EC4480. Weeks6-7: Multi Resolution Decomposition

Description.

Multi Resolution Signal Decomposition. An alternative representation of signals (both 1D and 2D) is based on a Multiresolution Decomposition. By this approach an image is separated into low frequency approximations and high frequency details. This decomposition is obtained using a combination of multirate low pass and high pass filters, in a configuration called Quadrature Mirror Filters.

Quadrature Mirror Filters. It turns out that the Quadrature Mirror Filters (QMF) structure presented yields a very sparse decomposition of the signal, both in the 1D as well as in the 2D domains, with low entropy. Families of FIR filters for QMF design can be derived from basic principles, which can be effectively implemented. In particular two families of filters are derived: Daubechies and Biorthogonal.

Apart from being efficient in terms of data compression, QMF decomposition also lends itself to an algorithm which can be applied effectively to nonlinear filtering of disturbances while still preserving high frequency details of the image itself.

Course Material:

- PPT Slides:
 - [Multi Resolution Decomposition 1](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/5-MultiResolution-1.ppt>
 - [Multi Resolution Decomposition 2](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/5-MultiResolution-2.ppt>
- Videos:
 - [General Approach to Multi Resolution Decomposition](#) 23.30min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-1-seg1.mp4>
 - [Quadrature Mirror Filters: Ideal Case](#) 14.24min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-1-seg2.mp4>
 - Simple FIR Filter Example 44.14min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-1-seg3.mp4>
 - [Quadrature Mirror Filters with FIR Filters](#) 27.10min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-2-seg1.mp4>
 - [Wavelet Decomposition of Images](#) 47.46min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-2-seg2.mp4>
 - [Matlab Wavelet Tool](#) 17.37min
<http://faculty.nps.edu/rcristi/EC4480/videos/5-Multiresolution-2-seg3.mp4>

- Assignment:

- Project 4 in Sakai ([*description*](#))

http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment4/Project4_AY16.doc

EC4480. Week8: *Motion Estimation in Video Images*

Description.

A very important problem in processing of video signals is to detect moving objects, and estimate the motion vector. This is important not only in target tracking, but also in video compression, where the stationary background is treated separately from the moving foreground.

We introduce two important techniques in motion estimation: the Optical Flow, which is computed over the entire frames, and the Kanade Lucas Tomasi (KLT) technique which tracks only points of interests in the video images, such as corners.

Course Material.

- PPT Slides:
 - [Optical Flow](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/6-Optical-Flow.ppt>
 - [Morphological Operations](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/7-morphological.ppt>
 - [Kanade Lucas Tomasi \(KLT\)](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/8-KLT-Tracking.ppt>
- Videos:
 - [Motion Detection and Optical Flow](#) 20.45min
<http://faculty.nps.edu/rcristi/EC4480/videos/6-OpticalFlow-seg1.mp4>
 - [Optical Flow in Simulink](#) 16.32min
<http://faculty.nps.edu/rcristi/EC4480/videos/6-OpticalFlow-seg2.mp4>
 - [Optical Flow in Simulink 2](#) 28.41min
<http://faculty.nps.edu/rcristi/EC4480/videos/7b-OpticalFlowSimulink.mp4>
 - [Morphological Operations](#) 36.54min
<http://faculty.nps.edu/rcristi/EC4480/videos/7-Morphological.mp4>
 - [Detect Points of Interest by KLT](#) 40.46min
<http://faculty.nps.edu/rcristi/EC4480/videos/8-KLT.mp4>
- Assignment:
 - Project 5 in Sakai ([description](#))
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5.docx>

- [Project 5 Video 1: Optical Flow](http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem1.mp4) 10.20min
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem1.mp4>
- [Project 5 Video 2: KLT](http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem2.mp4) 27.59min
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem2.mp4>
- [Project 5 Video 3: track a car](http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem3.mp4) 14.13min
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment5/Project5-problem3.mp4>

EC4480. Week9: Video Surveillance

Description.

An alternative way of detecting moving objects is by estimating the background from a number of video frames and then subtracting it from the videos themselves. This is based on the a-priori assumption that the background does not change between frames.

This problem can be extended also to video surveillance and detection of "abnormal behavior". For example, if you have a video of (say) the lobby of an airport, you see a lot of people moving or standing for a short amount of time, over a static background. However if someone leaves a piece of luggage for an amount of time, this luggage becomes part of the background which then changes. This change shows an "anomalous behavior" of the background which is clearly expected and would trigger a security alarm.

This can be extended to any situation in which, under normal circumstances, the intensities of the pixels exhibit given statistics (say a certain level of traffic on a street) and we want to detect "abnormal" cases, such increase or decrease in traffic.

Course Material:

- PPT Slides:
 - [Background Estimation](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/9-background.ppt>
 - [Video Surveillance](#)
<http://faculty.nps.edu/rcristi/EC4480/slides/12-Video-Surveillance.pptx>

- Videos:
 - [Background Estimation](#) 14.12min
<http://faculty.nps.edu/rcristi/EC4480/videos/10-BackgroundEstimation.mp4>
 - [Video Surveillance 1](#) 39.47min
<http://faculty.nps.edu/rcristi/EC4480/videos/11-VideoSurveillance-1.mp4>
 - [Video Surveillance 2](#) 15.30min
<http://faculty.nps.edu/rcristi/EC4480/videos/11-VideoSurveillance-2.mp4>

- Assignment:
 - Assignment 6 in Sakai ([description](#))

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment6/Project6.docx>

- [Project 6 Video](#)

14.33min

<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment6/Project6.mp4>

EC4480. Weeks10-11: *Multiscale Image Representation*

Description.

A fundamental problem in Computer Vision is to recognize various objects in a given scene. The challenge is that the same object in two different images can be rotated, be further or closer to the viewer, have occlusions or different illumination. Although the human brain seems to overcome these difficulties in a very efficient way, for a computer this becomes a very challenging problem.

One of the approaches, which seem to mimic some of the workings of our vision system, is the Multiscale approach. This is similar to the Multiresolution representation we saw earlier in the course, but the goals are different. By the Multiscale approach a gray scale image is represented with an added dimension (thus becoming three dimensional). The added dimension is a scaling factor, which accounts for the fact that an image can be viewed at different scales (small or large as if it were viewed from further away or close up). In this way, Points of Interest (PoI) are identified by local maxima of gradients in the two dimensions (x and y) and also the third dimension (scale). Then, for every PoI a vector of features is computed, which varies according to different algorithms.

This is at the basis of the SIFT and SURF algorithms, well known techniques in Computer Vision.

Course Material:

- PPT Slides:
 - [Multiscale Representation of Images](http://faculty.nps.edu/rcristi/EC4480/slides/10-MultiScale-Image-Representation-1.pptx)
<http://faculty.nps.edu/rcristi/EC4480/slides/10-MultiScale-Image-Representation-1.pptx>
 - [SURF and SIFT algorithms](http://faculty.nps.edu/rcristi/EC4480/slides/11-SIFT-SURF-algorithms.pptx)
<http://faculty.nps.edu/rcristi/EC4480/slides/11-SIFT-SURF-algorithms.pptx>
- Videos:
 - [Introduction to Multi Scale Representation](http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg1.mp4) 23.25min
<http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg1.mp4>
 - [Gaussian Filtering and Laplacian-1](http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg2-1.mp4) 25.22min
<http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg2-1.mp4>
 - [Gaussian Filtering and Laplacian-2](http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg2-2.mp4) 27.44min
<http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg2-2.mp4>

- [SIFT and SURF algorithms](http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg3.mp4) 46.45min
<http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg3.mp4>
- [RANSAC algorithm](http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg4.mp4) 42.40min
<http://faculty.nps.edu/rcristi/EC4480/videos/9-MultiScaleRepresentation-seg4.mp4>

- Assignment:
 - Assignment 7 in Sakai ([description](#), [PPT slides](#))
http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment7/Project_7_description-new.docx
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment7/Project7Notes.pptx>

 - [Project 7 Video](http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment7/Project7SURF.mp4) 16.16min
<http://faculty.nps.edu/rcristi/EC4480/ComputerAssignments/ComputerAssignment7/Project7SURF.mp4>